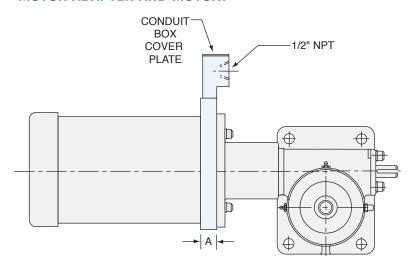




IN-LINE ENCODER IS INSTALLED BETWEEN THE MOTOR ADAPTER AND MOTOR.



For precise position sensing at the input shaft, an ActionJac™ in-line encoder option may be factory installed between the motor and motor adapter or Right-Angle Reducer. This lowcost option requires minimal space, leaving the extension shaft side of the jack free for clearance, for a rotary limit switch, or for coupling to another jack.

The in-line encoder's quadrature output design allows detection of both speed and direction of shaft rotation.

The ActionJac™ in-line encoder option requires an optional motor mount or Right-Angle Reducer.

Sensing speed range: 0 -10,000 rpm

Pulse Output: 60 Pulses per revolution Supply voltage: +12 Volts DC +/-5%

Supply current: 60 mA typical, 115 mA maximum Output drive capability: 250 mA per channel continuous

Maximum load: 50 ohms per channel

The encoder is face mounted between the motor and motor mount and will offset the length of the motor .61 inches for NEMA 56 and 140 frames and .88 inches for NEMA 180 and 210 frames.

FRAME SIZE	56C/140TC	180TC/210TC
OFFSET A	.61	.88

HOW TO ORDER AN IN-LINE ENCODER:

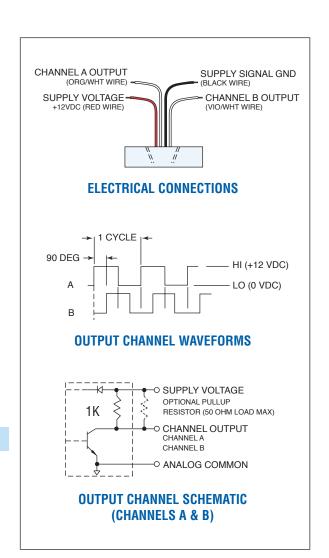
Specify the Worm Gear Screw Jack reference number, using the system described on page 296, 317, 336, 345 and 358.

EXAMPLE:

2.5-MSJ-U 6:1 / 10BT-1 / 2CA-4E / FT / 24.5 / SE

"E" anywhere in this field indicates Encoder-



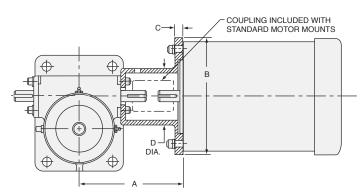






MOTORS AND MOTOR MOUNTS

MOTOR MOUNTS WITH AND WITHOUT BRAKEMOTORS



ActionJac[™] motor mount assemblies are designed for standard motors and include jaw type couplings. These assemblies are stocked for jack sizes 2.5, 5,10, 15 and 20 and are available for the jack sizes listed in the table. Non-standard motor mounts can be designed for special requirements including, special couplings,

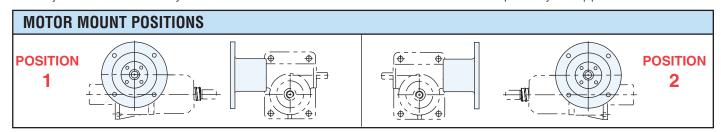
	STANDA	RD MOTOR	MOUNT	SIZES 8	& DIMEN	SIONS				
JACK	NEMA	ORDER CODE	DIMENSIONS							
SIZE (TONS)	FRAME SIZE	WITHOUT MOTOR	A	В	С	D				
	56C	X05	6.25	6.63	.63	3.50				
2.5	140TC	X14	6.25	6.63	.63	3.50				
	56C	X05	7.25	6.75	.56	3.75				
5	140TC	X14	7.25	6.75	.56	3.75				
	180TC	X18	8.00	9.25	.75	3.75				
	56C	X05	8.25	6.75	.50	4.38				
10, 15	140TC	X14	8.25	6.75	.50	4.38				
	180TC	X18	9.00	9.25	.75	4.38				
	56C	X05	8.66	6.75	.50	3.75				
00	140TC	X14	8.66	6.75	.50	3.75				
20	180TC	X18	9.00	9.25	.63	5.19				
	213TC	X21	9.68	8.88	.88	5.69				

small NEMA frame motors, DIN standard motors, stepper motor and servomotor designs. See page 290 for Servo Jack motor mount examples, contact Nook Industries for additional information.

Actionjac™ Worm Gear Screw Jacks can be ordered with industrial quality induction motors. Motors with internally and externally wired brake motors are available. Brake motors utilize an integral, spring actuated brake. Standard motors are 3-phase, 230-460 VAC, 60hz, 1725 rpm. Single-phase motors are 115-130 VAC, 60hz, 1725 rpm. All motors are rated for continuous duty. Specific duty motors, as wash down extended duty, may be supplied upon request.

See charts for order codes and motor mount dimensions. Additional motor mounts can be custom manufactured for other jack sizes, please contact Nook engineering.

CAUTION: Ball Screw Jacks are self-lowering. A brake of sufficient torque is required to hold the load with a ball screw jack. Be sure to verify that the brakemotor selected has sufficient brake torque for your application.



HOW TO ORDER A MOTOR ADAPTER WITH OR WITHOUT A BRAKEMOTOR

EXAMPLE WITHOUT MOTOR:



EXAMPLE WITH MOTOR:

2.5-BSJ-U 6:1 / 10BT-1 / SSE-2 / FT / 12.0 / S

Mounting Position (see above & for Right Angle Reducer see page 278)

Motor Order Code (see page 276)





ActionJac Worm Gear Screw jacks can be supplied with industrial quality. Brake motors include a spring actuated, electrically released braking mechanism which will hold a load when the power is off. In normal operation, power is applied and removed to the motor windings and brake release simultaneously.

If it is desired to operate the brake separately, as when used with a speed control, the brake needs to be wired externally. Standard for Reliance motors, special order for Baldor motors.

Standard motors are: 3 phase, 208-230 / 460 VAC, 60 Hz. 1725 rpm. Also available are single phase motors at: 115 / 230 VAC, 60 Hz. 1725 rpm. All motors are rated by continuous duty. Note: for inverter duty motors or additional options, contact Nook Industries.

For HOW TO ORDER see page 275.

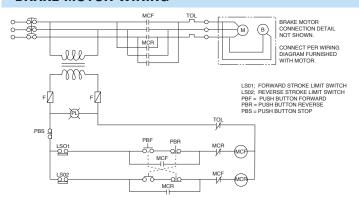
BALDOR: INTERNALLY WIRED BRAKE MOTOR ORDER CODE

MOTOR HP	STD. MOTOR 208-230/460 3PH	SINGLE PHASE 115/230 1PH	XT EXTRA TUFF 208-230/460 3PH	WASH DOWN MOTOR IP55 208-230/460 3PH	EXPLOSION PROOF • DIVISION 1 • CLASS 1,2 • GROUP F & G • 208/230/460 • 3PH
1/4	02BT	02BS	02BX	02BW	02BE
1/3	03BT	03BS	03BX	03BW	03BE
1/2	05BT	05BS	05BX	05BW	05BE
3/4	07BT	07BS	07BX	07BW	07BE
1	10BT	10BS	10BX	10BW	10BE
1-1/2	15BT	_	15BX	15BW	15BE
2	20BT	_	20BX	20BW	20BE
3	30BT	_	30BX	30BW	30BE
5	50BT	_	50BX	50BW	50BE
7-1/2	75BT	_	75BX	75BW	_

RELIANCE: EXTERNALLY WIRED BRAKE MOTOR ORDER CODE

MOTOR HP	STD. MOTOR 208-230/460 3PH	SINGLE PHASE 115/230 1PH	XT EXTRA TUFF 208-230/460 3PH	WASH DOWN MOTOR IP55 208-230/460 3PH	EXPLOSION PROOF DIVISION 1 CLASS 1,2 GROUP F & G 208/230/460 3PH
1/4	02RT	02RS	02RX	02RW	02RE
1/3	03RT	03RS	03RX	03RW	03RE
1/2	05RT	05RS	05RX	05RW	05RE
3/4	07RT	07RS	07RX	07RW	07RE
1	10RT	10RS	10RX	10RW	10RE
1-1/2	15RT	_	15RX	15RW	15RE
2	20RT	_	20RX	20RW	20RE
3	30RT	_	30RX	30RW	30RE
5	50RT	_	50RX	50RW	50RE
7-1/2	75RT	_	75RX	75RW	75RE

BRAKE MOTOR WIRING



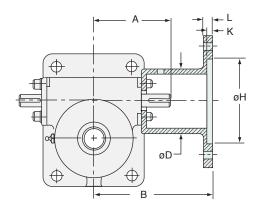
A typical wiring drawing is shown here, for a three-phase brake motor.

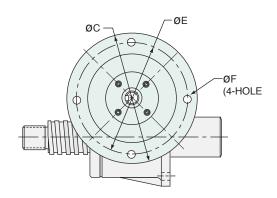
This example is for reference only, the correct wiring will vary for each application.





METRIC MOTOR MOUNTS





Other IEC Frame Motor Sizes available upon request, please contact factory

MODEL	IEC FRAME MOTOR SIZE	PART Number	A REF	В	ØC	ØD	ØE	ØF	ØH	К	L
EM05-BSJ	56B5	8026-01-00	57.5	100	120	64	100	8.5	80	3.5	7
EM05-MSJ	56B14	8020-01-00	57.5	100	80	64	65	6	50	3.0	6
	63B5	7825-01-00	76	114	140	70	115	9	95	4	8
EM1-BSJ	63B14	7826-01-00	76	114	90	70	75	6	60	3.5	8
EM1-MSJ	71B5	7821-01-00	76	120	160	85	130	9	110	4.5	10
	71B14	7822-01-00	76	120	105	85	85	7	70	4	10
	71B5	7785-01-00	90	135	160	85	130	9	110	4.5	10
EM2.5-BSJ	71B14	7773-01-00	90	135	105	85	85	7	70	4	10
EM2.5-MSJ	80B5	7787-01-00	90	145	200	85	165	11	130	4.5	12
	80B14	7774-01-00	90	145	120	85	100	7	80	4.5	12
	80B5	7795-01-00	115	180	200	98	165	11	130	4.5	12
EM5-BSJ	80B14	7791-01-00	115	170	120	96	100	7	80	4.5	12
EM5-MSJ	90B5	7790-01-00	115	180	200	96	165	11	130	4.5	12
	90B14	7796-01-00	115	180	140	96	115	9	95	4.5	12
	90B5	7798-01-00	140	207	200	116	165	11	130	4.5	12
EM10-BSJ	90B14	7799-01-00	140	207	140	116	115	9	95	4.5	12
EM10-MSJ	100B5	7802-01-00	140	217	250	116	215	13	180	5	14
	100B14	7803-01-00	140	217	160	116	130	9	110	5	14
EM20-BSJ	100B5	7809-01-00	150	230	250	134	215	13	180	5	14
EM-20-MSJ	100B14	7811-01-00	150	230	160	134	130	9	110	5	14

RIGHT ANGLE REDUCERS



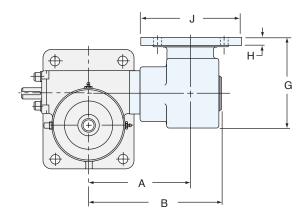


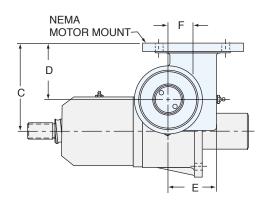
The Right-Angle Reducer is a compact, high quality worm gear reducer enclosed in a ductile iron housing. The reducer mounts directly to the input side of the jack. Motors mount quill-style to a standard NEMA C-face.

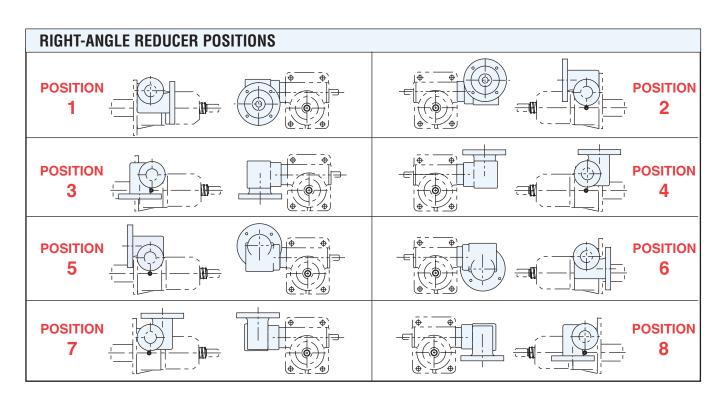
The right angle reducer is a secondary worm gear reducer that reduces speed and increases torque to the input of the jack. If motor clearance is an issue, a right angle reducer may be added to most jacks to optimize motor orientation.

Right Angle Reducers may be ordered installed on the standard ActionJac™ Machine Screw and Ball Screw Jacks listed below and are available with or without brakemotors.

Consult the data charts for jack capacity when a Right-Angle Reducer is used. Ratings given on the chart may differ when a Right-Angle Reducer is installed on Keyed or Anti-Backlash Machine Screw Jack models. Special consideration must be given when installing onto a Double-Clevis Jack due to the additional weight of the reducer.











RIGHT ANGLE REDUCERS

RIGHT-AN	IGLE RE	DUCERS F	OR BAL	L SCREV	N JACK	S											
JACK MODEL-	DEDITOED	TRAVEL RATE	BRAKE	DYNAMIC	OF	RDER COE)E**	MOTOR			RED	UCER	DIM	ENSIO	NS		
RATIO	RATIO	IN/MIN. @ 1725 RPM	MOTOR HP	CAPACITY* (LBS.)	W/1-PH MOTOR	W/3-PH MOTOR	WITHOUT MOTOR	SIZE	A	В	C	D	Ε	F	G	Н	J
2.5-BSJ-6:1	6:1	12.0	1/2	5,000	05BSR6	05BTR6	X05R6										
2.0-000-0.1	12:1	5.99	1/3	5,000	03BSR12	03BTR12	X05R12										
0 5 001 04.4	6:1	2.99	1/4	5,000	02BSR6	02BTR6	X05R6										
2.5-BSJ-24:1	12:1	1.48	1/4	5,000	02BSR12	02BTR12	X05R12	56C	5.63	7.44	5.44	3.69	3.31	1.750	5.88	.50	6.69
2.5HL-BSJ-6:1	6:1	47.9	1	2,370	10BSR6	10BTR6	X05R6										
2.0HL-B0J-0.1	12:1	24.0	1	4,870	10BSR12	10BTR12	X05R12										
E 001 04	6:1	22.7	1	6,300	10BSR6	10BTR6	X05R6										
5-BSJ-6:1	12:1	11.3	1	10,000	10BSR12	10BTR12	X05R12										
E DO L 04-4	6:1	5.67	1	10,000	10BSR6	10BTR6	X05R6	56C	6.50	8.50	5.88	3.69	3.31	1.750	5.88	.50	6.69
5-BSJ-24:1	12:1	2.83	1/2	10,000	05BSR12	05BTR12	X05R12		0.50	0.00	0.00	0.00	0.01	1.700	0.00	.00	0.00
5HL-BSJ-6:1	6:1	47.9	1	3,000	10BSR6	10BTR6	X05R6										
5HL-BSJ-24:1	6:1	12.0	1	7,400	10BSR6	10BTR6	X05R6										
10-BSJ-8:1	6:1	17.0	1	7,700	10BSR6	10BTR6	X05R6										
10-003-0.1	12:1	8.50	1	13,000	10BSR12	10BTR12	X05R12										
10-BSJ-24:1	6:1	5.67	1	15,000	10BSR6	10BTR6	X05R6	56C	7.25	9.25	6.29	3.69	3.31	1.750	5.88	.50	6.69
10-003-24.1	12:1	2.83	1	20,000	10BSR12	10BTR12	X05R12										
10HL-BSJ-8:1	6:1	35.9	1	3,600	10BSR6	10BTR6	X05R6	1									
20-BSJ-8:1	8:1	13.5	3	40,000	N/A	30BTR8	X18R8										
20-BSJ-24:1	8:1	4.49	2	40,000	N/A	20BTR8	X18R8	180TC	9.00	11.75	9.00	6.12	5.38	2.875	9.00	.88	9.12
20HL-BSJ8:1	8:1	26.9	5	40,000	N/A	50BTR8	X18R8	10016	9.00	11./5	9.00	0.12	0.08	2.0/0	9.00	.00	9.12
20HLBSJ-24:1	8:1	8.98	3	40,000	N/A	30BTR8	X18R8										

RIGHT-AN	IGLE RE	DUCERS F	OR MAG	CHINE SO	CREW J	ACKS											
JACK MODEL-	REDUICER	TRAVEL RATE	BRAKE	DYNAMIC	0	RDER CO	DE	MOTOR			REDI	UCER	DIM	ENSIO	NS		
RATIO	RATIO	IN/MIN. @ 1725 RPM	MOTOR HP	CAPACITY* (LBS.)	W/1-PH MOTOR	W/3-PH MOTOR	WITHOUT MOTOR	SIZE	A	В	C	D	E	F	G	Н	J
2.5-MSJ-6:1	6:1	12.0	1	4,610	10BSR6	10BTR6	X05R6										
2.0 11100 0.1	12:1	5.99	3/4	5,000	07BSR12	07BTR12	X05R12	56C	5.63	7.44	5 11	3 60	3.31	1750	5.88	.50	6.69
2.5-MSJ-24:1	6:1	2.99	1/2	5,000	05BSR6	05BTR6	X05R6		3.00	1.44	J.44	0.00	0.01	1.700	3.00	.50	0.03
2.3-M03-24.1	12:1	1.48	1/3	5,000	03BSR12	03BTR12	X05R12										
5-MSJ-6:1	6:1	18.0	1	3,000	10BSR6	10BTR6	X05R6						3.31	1.750			
J-1010J-0.1	12:1	8.98	1	5,000	10BSR12	10BTR12	X05R12	56C	6.50	8.50	5.88	3.69			5.88	.50	6.69
5-MSJ-24:1	6:1	4.49	1	6,000	10BSR6	10BTR6	X05R6		0.00			0.00	0.00	0.0.	00	0.00	
J-1910J-24.1	12:1	2.25	1	10,000	10BSR12	10BTR12	X05R12										
10-MSJ-8:1	6:1	18.0	1	3,000	10BSR6	10BTR6	X05R6										
10-14199-0.1	12:1	8.98	1	5,000	10BSR12	10BTR12	X05R12	56C	7.25	9.25	6.29	3.69	3.31	1.750	5.88	.50	6.69
40 MC L 24.4	6:1	5.99	1	6,000	10BSR6	10BTR6	X05R6										
10-MSJ-24:1	12:1	2.99	1	10,000	10BSR12	10BTR12	X05R12										
00 MC L 0.4	8:1	13.5	71/2	40,000	N/A	75BTR8	X21R8	210TC									
20-MSJ-8:1	8:1	13.5	5	22,500	N/A	50BTR8	X18R8	10070	9.00	11.75	9.00	6.12	5.38	2.875	9.00	.88	9.12
20MSJ-24:1	8:1	4.49	3	35,500	N/A	30BTR8	X18R8	180TC									

^{*}Full nominal static capacity of jack is retained

HOW TO ORDER A RIGHT-ANGLE REDUCER:

Right-Angle Reducer ratio, mounting position and brakemotor size and type must be specified. The data chart above gives order codes for Right-Angle Reducers with and without brakemotors. Insert the order code and mounting position as shown on page 296, 317, 336, 345 and 358.

EXAMPLE: 2.5-BSJ-U 6:1 / **05BTR6 - 2** / 2CA-2 / FT / 24.5 / S



^{**}Motor specified is internally wired brake motor, for additional motor options see page 276





STANDARD AND SPECIAL BELLOWS BOOTS

Bellows boots are available for all sizes and configurations of ActionJac[™] Worm Gear Screw Jacks. A boot protects the lifting shaft from contamination and helps retain lubricant to ensure long jack life.

Standard boots are sewn from black neoprene-covered nylon fabric for oil, water and weather resistance and are acceptable for use in -60° to +220° F environments. Optional materials are available for specific operating conditions (see chart).

Guides are recommended for all horizontal applications where travel exceeds 24 inches or if the boot needs to remain centered around the screw. The recommended number of guides is one guide for each 24 inches of travel length.

EXAMPLES: 12 inches of travel = no guides, 24 inches of travel = one guide, 47 inches of travel = one guide, 48 inches of travel = two guides, etc.).

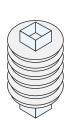
Standard boots are furnished with tie straps for jacks with greater than 65 inches travel. Tie straps are attached from convolution to convolution and help the boot extend uniformly.

SPECIAL BOOT MATERIALS

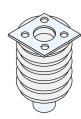
DESCRIPTION	TEMPERATURE RANGE	APPLICATION COMMENTS
HYPALON-COATED NYLON	-60° TO +300° F	CHEMICAL RESISTANCE, WASH DOWN
SILICONE COATED FIBERGLASS	-100° TO +550° F	HIGH TEMPERATURE
ALUMINUM-COATED FIBERGLASS	-100° TO +550° F	HIGH TEMPERATURE, HOT CHIPS, WELDING SPLATTER

Note: Retracted boot length may increase with some special materials.

SPECIAL END CONFIGURATIONS







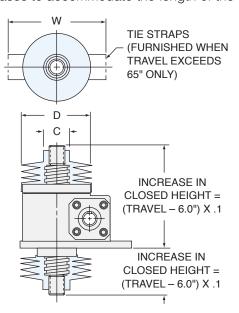
SQUARE CUFF

FLANGE END

SQUARE FLANGE

BELLOWS BOOTS TRANSLATING SCREW JACKS

The end cuff is designed to fit standard end fittings, the top plate and the clevis end. When jack travel is greater than 6 inches, lift screw closed height increases to accommodate the length of the



collapsed boot convolutions. For standard boots the increase in closed height is calculated using the formula shown.

JACK M	IODEL	0	В		MAN CODEM
BALL SCREW	MACHINE SCREW	C DIA	D DIA	W	MAX. SCREW DIA (REF.)
0.5-BSJ	ALL MJ	1.00*	4.00*	5.50	0.63
1-BSJ	1-MSJ	1.25	4.25	5.75	0.75
2,2.5 & 3-BSJ	2, 2.5-MSJ	1.50	4.50	6.00	1.16
5, 10-BSJ	5-MSJ	2.00	5.00	6.50	1.50
_	10-MSJ	2.50	5.50	7.00	2.00
_	15-MSJ	2.75	5.75	7.25	2.25
20-BSJ	20-MSJ	3.00	6.00	7.50	2.50
30-BSJ	30-MSJ	4.50	7.50	8.00	3.38
_	35-MSJ	5.00	8.00	9.50	3.75
50,75 & 100-BSJ	_	6.00	9.00	10.50	4.00
_	50-MSJ	6.50	9.50	11.00	4.50
_	75-MSJ	7.00	10.00	11.50	5.00
_	100-MSJ	8.00	11.00	12.50	6.00

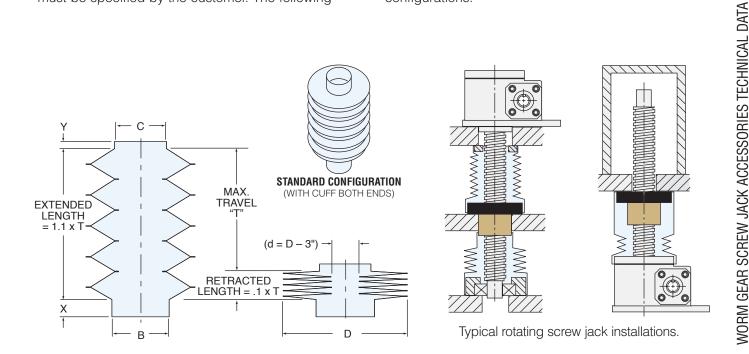
(*BOOT w/GUIDES: C=1.25/D=4.25)



BELLOWS BOOTS FOR ROTATING SCREW JACK

Installation arrangements for rotating worm gear screw jacks vary, therefore boots for rotating jacks must be specified by the customer. The following

figures show typical installations for rotating screw jacks, standard dimensions and custom end configurations.



HOW TO ORDER BOOTS FOR A TRANSLATING AND ROTATING SCREW JACK

Boots may be ordered using the reference number system as shown on pages 296, 317, 336, 345 and 358. For special material boots add "M" to the reference number and add the description.

EXAMPLE:

5-MSJ-U 6:1 / SSE-1 / SSE-2 / FT / 36.0 / BGS B = Standard Boot -G = with Optional Guide(s) -

Boots for upright rotating and inverted rotating jacks are ordered as separate line items.

Typical rotating jack applications require two boots, one between the housing and the travel nut and one from the travel nut to the end of the lift shaft. Each boot for a rotating screw jack is ordered as a separate line item. To order boots for a rotating screw jack, select the outside diameter "D" from the chart on the facing page and specify cuff dimensions and travel per the diagram using the reference number as shown below.

EXAMPLE:







Every motorized Worm Gear Screw Jack must be controlled so that power to the motor is turned off and the brake engaged before the limits of mechanical travel are reached.

The ActionJac™ rotary limit switch senses extension shaft rotation and provides switch contact closures that can be used to control motors.

This sturdy, durable assembly is available with two or four circuits or two circuits and a potentiometer. Each circuit has a separate rotating cam that actuates a high quality switch. The switch actuation may be individually and infinitely adjusted anywhere within the travel of the jack.

These assemblies contain gear reducers with ratios that vary according to the model and travel of the jack. Nook selects ratios that result in maximum cam rotation for best accuracy, repeatability and minimum hysteresis. In most cases, with full travel of the actuator, the cam will rotate 3/8 to 7/8 of a revolution to actuate a switch. In the event that the cam continues to rotate, the switch returns to its original state after approximately 25° of rotation, with no damage to the limit switch assembly.

The 2-circuit switch assembly is useful for limiting the maximum and minimum extension. The 4-circuit assembly gives the possibility of additional signals for other user purposes. The potentiometer version is used to provide an analog signal for sensing jack position.

Single Pole Double Throw (SPDT) switches are standard and Double Pole Double Throw (DPDT) switches are



optional. These assemblies are dust protected and meet NEMA 4 and 5 standards for oil and water tightness.

The ActionJac[™] rotary limit switch assembly is mounted to the extension shaft side of the ActionJac[™] Worm Gear Screw Jack opposite the input.

The rotary limit switch is available for ActionJac[™] Worm Gear Screw Jack sizes 2 tons and larger. Most jack models have close and extended mounts to provide clearance around the switch housing. See the following chart for dimensions.

Switches are factory installed to assure proper assembly in the correct orientation for the specified mounting position.

CAUTION: Limit switches are not adjusted at the factory. Switches should be set during installation.

CODE

2CA

2CC

4CA

4CE

PTA

PTC

SWITCH TYPE

SPDT

DPDT

SPDT

DPDT

SPDT

DPDT

OF CIRCUITS

2

2

4

4

2

POTENTIOMETER

NO

NO

NO

NO

YES

YES

HOW TO ORDER ROTARY LIMIT SWITCH:

SPECIFY:

282 nookindustries.com

- Limit Switch code (see table to right)
- Mounting Position (1 through 8 see page 283)
- Close or Extended Mount (C or E)

Insert the correct designation in the ActionJac[™] Worm Gear Screw Jack reference number (see page 296 and 317 for more information on jack reference numbers).

EXAMPLE: 2.5-MSJ-U 6:1 / 103-1 / **2CA-4E** / FT / 24.5 / S

Extension shaft designation

Examples of rotary limit switch designations:

2CA-4C = Rotary Limit Switch, 2-circuit, SPDT, position 4, close mount

4CE-1E = Rotary Limit Switch, 4-circuit, DPDT, position 1, extended mount

PTA-8C = Rotary Limit Switch with potentiometer, 2 SPDT's, position 8, close mount

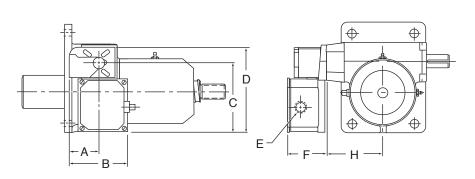
C = Close mount on E = Extended mount (see following page)"dash" number designates mounting position

IMPORTANT: These designation numbers are not complete part numbers. These assemblies contain gear reducers with ratios that vary according to the model and travel of the jack. If you are ordering a replacement switch assembly, complete information on the jack is required.





ROTARY LIMIT SWITCH



OLDOLUTO	DIMENSIONS							
CIRCUITS	Α	В	C	D	Е	F		
LS-2C 2 CIRCUIT	2.46	5.25	6.24	7.62	3/4-NPT	3.25		
LS-4C 4 CIRCUIT	2.46	5.25	8.24	9.62	1-NPT	3.88		
LS-2PT 2 CIRCUIT WITH POTENTIOMETER	2.46	5.25	8.24	9.62	1-NPT	3.88		

MODEL	DIM.H CLOSE MOUNT	DIM.H Ext. Mount	CLOSE MOUNT POSITIONS
2-BSJ & MSJ	N/A	3.56	ALL
2R, 2.5-BSJ & MSJ	2.75	3.56	ALL
3-BSJ	N/A	3.56	ALL
5-BSJ & MSJ	3.56	4.56	ALL
5R-BSJ & MSJ	4	5.06	ALL
10, 15-BSJ & MSJ	3.88	5.56	ALL
20-BSJ & MSJ	4.41	5.81	ALL
30, 35-MSJ	5.25	7.06	ALL
50-BSJ & MSJ	6.25	11.06	1,2,4,7
75-BSJ & MSJ	7.25	12.06	ALL
100-BSJ & MSJ	8.25	12	1,2,4,7

ROTARY LIMIT	SWITCH POSITIONS	_	
POSITION 1		*	POSITION 2
POSITION 3			 POSITION 4
POSITION 5			POSITION 6
POSITION 7			POSITION 8

ELECTRICAL RATINGS:

WIRING DIAGRAMS:

SWITCHES:

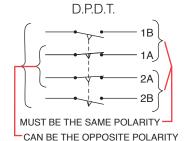
DC Current — 115 Volts SPDT, .50 amps

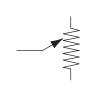
DPDT, .80 amps

AC Current — 115 Volts SPDT, 15 amps

DPDT, 10 amps

S.P.D.T. В MUST BE THE SAME POLARITY





POTENTIOMETER

10-TURN POTENTIOMETER:

0-500 OHM, 2 Watt

NOTE: While the 10-turn potentiometer is rated for 0-500 Ohms, as implemented in the rotary limit switch assembly, it can not and should not operate over its full range. Minimum and maximum resistance values can not be known until the unit is installed and final travel limit adjustments have been made, therefore, the device connected to the potentiometer should include provisions for trimming to compensate for these values.

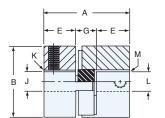




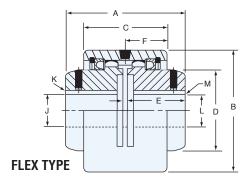
Jacks used alone or in multiple arrangements require couplings to transmit power to the input shaft. Nook Industries provides jaw type and flex type couplings for use with jacks. The selection process for couplings includes the following steps:

- 1) Refer to the jack specification tables to determine torque requirements per jack for your application.
- 2) Determine total coupling capacity required by multiplying the torque required per jack by the number of jacks to be driven by the coupling.
- 3) Check the torque required against maximum torque rating as shown in the table. Select a coupling with a maximum torque greater than the application torque.
- 4) If using flex type couplings, full-flex couplings should be used for close coupled arrangements. For floating shaft applications, use two Flex-Rigid couplings. The rigid half should be mounted on the floating shaft.

All jacks, shafts, couplings and motor should be carefully aligned for maximum performance. Couplings with bores other than those specified are available upon request.



JAW TYPE



JACK PART NO.	MAX. TORQUE	APPROX.		С	OUPLII	NG DIN	IENSIO	BORE SIZES					
JAW TYPE	RATING INLBS.	WT. LBS.	Α	В	С	D	E	F	G	J	KEYWAY K	L	KEYWAY M
C-2020-01	38.5	.25	1.66	1.06	_	_	.56	_	.53	.376	_	.376	_
C-2025-01	126	.75	25/32	1.75	_	_	13/16	_	.53	.5005 .5000	1/8 X 1/16	.5005 .5000	1/8 X 1/16
C-2025-05	126	.75	25/32	1.75		_	13/16	_	.53	.5005 .5000	1/8 X 1/16	.6255 .6250	1/8 X 1/16
C-2025-02	126	.75	25/32	1.75		_	13/16	_	.53	.5005 .5000	1/8 X 1/16	.7505 .7500	³ / ₁₆ X ³ / ₃₂
C-2025-03	126	.75	25/32	1.75	_	_	13/16	_	.53	.6255 .6250	1/8 X 1/16	.6255 .6250	1/8 X 1/16
C-2025-04	126	.75	25/32	1.75	_	_	13/16	_	.53	.6255 .6250	1/8 X 1/16	.7505 .7500	³ / ₁₆ X ³ / ₃₂
C-2025-06	126	.75	2 ⁵ /32	1.75	_	_	13/16	_	.53	.7505 .7500	3/16 X 3/32	.7505 .7500	³ / ₁₆ X ³ / ₃₂

JACK PA	ART NO.	MAX. TORQUE	MAX. TORQUE APPROX. COUPLING DIMENSIONS									BORE SIZES			
	FLEX-RIGID	RATING	WT. LBS.	A	В	С	D	E	F	G	J	KEYWAY K	L	KEYWAY M	
C-1800-04	C-1805-04	2500	5	31/8	35/16	2	2	11/2	1	1/8	.4995 .4990	1/8 X 1/16	.7495 .7490	3/16 X 3/32	
C-1800-01	C-1805-01	2500	5	31/8	35/16	2	2	11/2	1	1/8	.4995 .4990	1/8 X 1/16	.9995 .9990	1/4 X 1/8	
C-1800-05	C-1805-05	2500	5	31/8	35/16	2	2	11/2	1	1/8	.7495 .7490	3/16 X 3/32	.7495 .7490	3/16 X 3/32	
C-1800-02	C-1805-02	2500	5	31/8	35/16	2	2	11/2	1	1/8	.7495 .7490	3/16 X 3/32	.9995 .9990	1/4 X 1/8	
C-1800-03	C-1805-03	2500	5	31/8	35/16	2	2	11/2	1	1/8	.9995 .9990	1/4 X 1/8	.9995 .9990	1/4 X 1/8	
C-1810-01	C-1815-01	7500	8	33/4	33/4	217/32	23/8	113/16	1 17/64	1/8	1.2495 1.2490	1/4 X 1/8	1.2495 1.2490	1/4 X 1/8	
C-1810-02	C-1815-02	7500	8	33/4	33/4	217/32	23/8	113/16	117/64	1/8	1.3745 1.3740	5/16 X 5/32	1.2495 1.2490	1/4 X 1/8	
C-1810-03	C-1815-03	7500	8	33/4	33/4	217/32	23/8	113/16	117/64	1/8	1.4995 1.4990	3/8 X 3/16	1.2495 1.2490	1/4 X 1/8	





POWERSHAFT™ LINK SHAFTING

ActionJac™ LinkJac™ Line Shafting is used to interconnect the input shafts of ActionJac™ Worm Gear Screw Jacks used in a multiple arrangement. The shafts transfer the torque from the motor to the jack or from jack to jack.

Nook Industries LinkJac[™] Line Shafting is made from steel and is available in standard lengths up to 144". Custom end machining and other diameters are available, contact Nook Industries for information.

SELECTION:

There are two major concerns when selecting interconnect shaft:

- Critical Speed: How fast will the shaft be turning?
- Torque: How much load will the shafts be carrying?

The two characteristics of a LinkJac[™] Line Shaft which can be varied to accommodate these requirements are:

- Length of the shaft
- Diameter of the shaft

When selecting a LinkJac[™] Line Shaft, use the largest diameter or shortest length which satisfies both of the following equations.

If you know the length and operating speed of the shaft:

$$\frac{L^2 \times N}{4.76 \times 10^6}$$

Minimum Diameter of the LinkJac™ Shaft in inches

WHERE:

L = length of unsupported shaft in inches N = operating speed in revolutions per minute

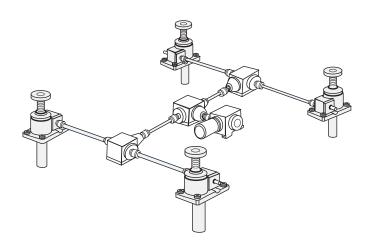
If you know the torque to be transmitted and the length of the shaft:

(T x L x 51 x 10⁻⁶).25 = Minimum Diameter of the LinkJac[™] Shaft in inches

WHERE:

T = torque in inch-pounds

L = total length of shaft in inches



DESIGN INFORMATION:

- The length used in the Speed-Length-Diameter Calculation is the supported length of the shaft. If support bearings are used on the shaft, the length is the longest unsupported length between bearings.
- The formulas above give a theoretical value of critical speed. Alignment, straightness and stiffness of the system all contribute to determining the actual value.
- The formula used for finding minimum diameter when torque and length are known is based on an allowable twist of 1°. Restricting the twist allows for better synchronization of ActionJac™ motion.
- The torque in the system is also limited by the torque capacity of the coupling.
- Allow 1/8 inch spacing between the jack input shaft and the LinkJac™ shaft inside the coupling.
- For some combinations of couplings and jacks, the radius of the suggested coupling is larger than the distance from the center of the worm shaft to the base.
- Nook Industries offers a range of couplings for use with LinkJac[™] and ActionJac[™] products in both floating shaft and supported shaft applications. See page 284 for more information.

LINKJAC™ SHAFT	NOMINAL	KEYWAY	COUPLING SERIES						
PART NUMBER	DIAMETER	KLIWAI		C-1810 / 1815					
LJ-8	1/2	1/8 x 1/16							
LJ-12	3/4	3/16 x 3/32							
LJ-16	1	1/4 x 1/8							
LJ-24	1 1/2	3/8 x 3/16							

WORM GEAR SCREW JACK ACCESSORIES TECHNICAL DATA

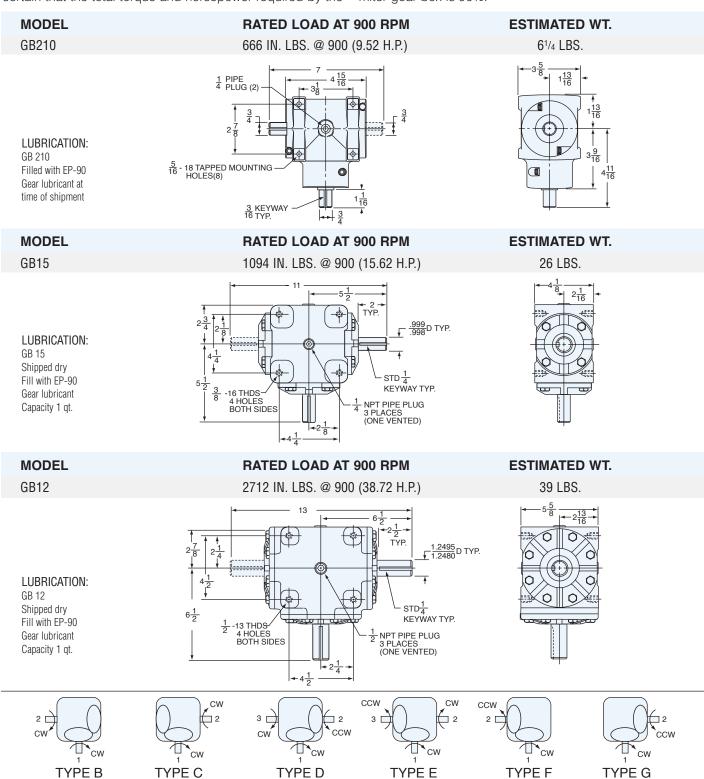
STANDARD MITER GEAR ASSEMBLIES GEAR RATIO 1:1





Jacks may be used in multiple arrangements by connecting shafting, couplings and gear boxes to simultaneously transmit power to the input shafts of the jacks. Nook Industries provides gearboxes for use with jacks. Make certain that the total torque and horsepower required by the

arrangement does not exceed the ratings of the box. Miter gear boxes can be operated up to 900 rpm. Higher speeds are permissible at lower torque ratings. Noise levels may increase at higher speeds. The operating efficiency of a miter gear box is 90%.



Gears are forged alloy steel. Shafts are stressproof steel ground and polished. Clockwise (CW) and counterclockwise (CCW) notations indicate direction of shaft rotation when facing outer end of shaft. All shaft arrangements will operate opposite direction for that shown. To order specify model number and desired shaft arrangement.



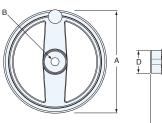


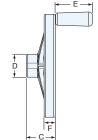


HANDWHEELS

A handwheel is a convenient solution for manually operating a jack when using machine screw jacks in intermittent positioning applications. Handwheels are available in a range of diameters from 4 to 10 inches and can be adapted for use on jacks from the MJ series up to the 20 ton capacity model.

NOTE: Handwheels do not include a brake. Handwheels are not recommended for use with ball screw jacks. When using handwheels with a jack that can backdrive (12:1 and lower) an additional locking mechanism may be required to prevent "creep".





HANDWHE	L SPECIF	ICATIONS		meas	surements in	inches	
JACK SIZE	А	В	С	D	E	F	PART # METAL
MJ	4	.375	1 1/2	1 3/16	1 5/8	5/8	H043
4 MOI	4	.50	1 1/2	1 3/16	1 5/8	5/8	H044
1-MSJ	6	.50	2	1 9/16	2 9/16	3/4	H064
0 MOI	4	.50	1 1/2	1 3/16	1 5/8	5/8	H044
2-MSJ	6	.50	2	1 9/16	2 9/16	3/4	H064
0.5.840.1	4	.50	1 1/2	1 3/16	1 5/8	5/8	H044
2.5-MSJ	6	.50	2	1 9/16	2 9/16	3/4	H064
	6	.75	2	1 9/16	2 9/16	3/4	H066
5-MSJ	8	.75	2 1/4	1 25/32	2 15/16	7/8	H086
	10	.75	3	2 1/4	3 15/16	1	H106
10-MSJ	8	1	2 1/4	1 25/32	2 15/16	7/8	H088
10-1/183	10	1	3	2 1/4	3 15/16	1	H108
15-MSJ	8	1	2 1/4	1 25/32	2 15/16	7/8	H088
19-1/18J	10	1	3	2 1/4	3 15/16	1	H108
20-MSJ	8	1	2 1/4	1 25/32	2 15/16	7/8	H088
20-1910J	10	1	3	2 1/4	3 15/16	1	H108

HOW TO ORDER A JACK WITH A HANDWHEEL

EXAMPLE:

2.5-MSJ-U 24:1 / H064-1 / SSE-2 / FT / 12.0 / S

Mounting Position (see page 317) Part Number (from chart above)







COUNTERS

For precise position display, a range of digital position indicators are available for use with ActionJac™ Worm Gear Screw Jacks. These indicators measure the rotation of the input shaft and display a corresponding position in a counter window. The display value per input shaft revolution is variable and is achieved through a series of gear reductions configured to accommodate different jack ratios, lift shaft leads and travel distances. Contact Nook Industries to determine actual readout scaling available for your application.

HOW TO ORDER COUNTER:

SPECIFY: • Determine Mounting Position

· Count Increase or Decreases with Extension of Shaft

EXAMPLE: 2.5-MSJ-U 6:1 / SSE-1 / CTI-2 / FT / 24.5 / S

Examples of counter designations:

Extension shaft designation

CTI-2 = Counter, which increases with extension of the Lift Shaft, position 2 Dash number designates mounting position

CEI CTI C_I* **CED** CTD C D'

CEI = Counts INCREASE with extension of travel, without shaft extension

Counts **DECREASES** with extension of travel, without shaft extension

Counts INCREASE with extension of travel, with worm shaft extension

Counts **DECREASES** with extension of travel, with worm shaft extension

Counts INCREASE with extension of travel, with 4" handwheel*

CAD = Counts DECREASES with extension of travel, with 4" handwheel*

CBI = Counts **INCREASE** with extension of travel, with 6" handwheel*

CBD = Counts DECREASES with extension of travel, with 6" handwheel*

CCI = Counts **INCREASE** with extension of travel, with 8" handwheel*

CCD = Counts DECREASES with extension of travel, with 8" handwheel*

CDI = Counts INCREASE with extension of travel, with 10" handwheel*

Counts **DECREASES** with extension of travel, with 10" handwheel*

*See handwheel page 287 to select the correct size for jack model

COUNTER	POSITIONS						
POSITION 1	POSITION 2						
POSITION 3	POSITION 4						
POSITION 5 – NOT AVAILABLE	POSITION 6 – NOT AVAILABLE						
POSITION 7	POSITION 8						







Nook ActionJac[™] Trunnion adapter plates allow for easy installation in applications where the jack moves through an arc during operation. These jacks are typically configured with motor mounts or right angle reducers.

Trunnion adapter plates bolt to the jack flange and have precision bores for trunnion pins.

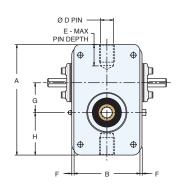
TRUNNION ADAPTERS

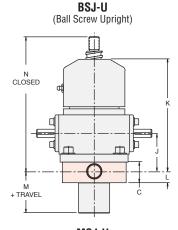
Design Information

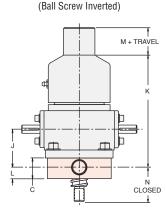
The trunnion pins should be supported to within 1/16 inch of the trunnion adapter plate. See the "A" dimension in the table for the width of the mounting plate. The maximum distance between the trunnion pin support mounting surfaces should be less than or equal to the "A" dimension plus 0.13 inches.

The trunnion pins should be ground to the "D" diameters shown in the table. The trunnion pins should be made from steel with a hardness greater than 30 HRC and a yield strength greater than 60,000 psi.

BSJ and MSJ Trunnion Bottom View

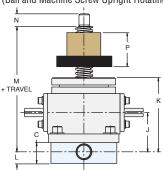




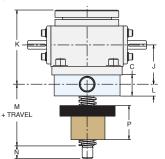


BSJ-I

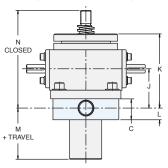
BSJ-UR and MSJ-UR (Ball and Machine Screw Upright Rotating)

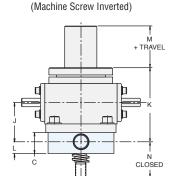


BSJ-IR and MSJ-IR (Ball and Machine Screw Inverted Rotating)



MSJ-U (Machine Screw Upright)





MSJ-I

JACK MODEL		COMMON DIMENSIONS FOR U, I , UR & IR										PRIGH	IT	IN	VERTE	D	UPF	RIGHT	ROTAT	ING	INVERTED ROTATING			
TRUNNION Part #	Α	В	C	D	Ε	F	G	Н	J	L	K	M	N	K	M	N	K	M	N	Р	K	M	N	Р
2.5-MSJ TA-0025	6.50	3.88	1.25	.7491 .7479	1.25	.13	1.750	2.50	2.32	.69	4.38	1.38	5.75	4.38	.69	2.06	4.38	7.38	.75	2.00	4.38	3.69	.75	2.00
5-MSJ TA-0050	8.25	5.75	1.50	<u>.9991</u> .9979	1.50	.13	2.188	3.13	2.94	.81	5.44	1.44	7.69	5.44	.63	3.06	5.44	9.44	1.00	3.00	5.44	4.81	1.00	3.00
10-MSJ TA-0100	9.00	7.00	1.97	1.2488 1.2472	1.38	.13	2.600	3.00	3.13	1.09	5.75	1.72	7.75	5.75	.63	3.12	5.75	9.75	2.00	3.00	5.75	5.12	2.00	3.00
20-MSJ TA-0200	11.25	8.00	2.22	1.4988 1.4972	1.75	.13	2.875	4.25	4.25	1.22	7.75	1.84	10.25	7.75	.63	3.75	7.75	12.25	2.50	3.50	7.75	5.75	2.50	3.50
2.5-BSJ TA-0025	6.50	3.88	1.25	.7491 .7479	1.25	.13	1.750	2.50	2.32	.69	6.81	2.31	8.19	6.81	1.63	2.06	4.38	7.75	1.13	2.38	4.38	4.06	1.13	2.38
5-BSJ TA-0050	8.25	5.75	1.50	<u>.9991</u> .9979	1.50	.13	2.188	3.13	2.94	.81	10.00	2.31	11.88	10.00	1.75	3.06	5.44	10.75	1.50	4.31	5.44	6.13	1.50	4.31
10-BSJ TA-0100	9.00	7.25	2.00	1.2488 1.2472	1.50	.13	2.600	3.00	3.13	1.12	10.00	2.75	12.25	10.00	1.63	3.37	5.75	11.06	1.50	4.31	5.75	6.44	1.50	4.31
20-BSJ	11.25	8.00	2.25	1.4988	1.75	.13	2.875	4.25	4.25	1.25	15.75	3.63	18.25	15.75	2.38	3.75	7.75	15.50	2.75	6.75	7.75	9.00	2.75	6.75

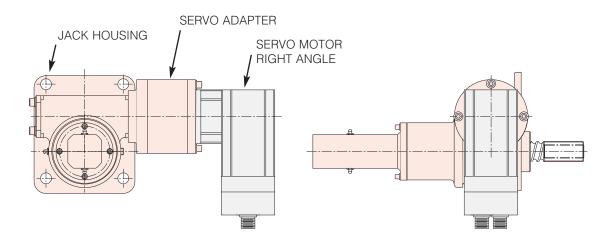




ActionJac™ Servo Jacks offer the ability to attach a servo motor to a ball screw or machine screw jack. Using an ActionJac™ Worm Gear Screw Jack with a servo motor increases control of acceleration, de-acceleration, travel rate and positioning accuracy compared with standard NEMA framed motors.

Illustrated below are two examples of jacks with servo motor adaptors manufactured by Nook Industries. Custom Servo Motor Adaptors are designed to accommodate any specified coupling and servo motor. Servo Jacks can be delivered as a complete assembly, including a vendor specified servo motor. Contact Nook Industries for further assistance with jack applications requiring servo motors.

KEYED INVERTED BALL SCREW SERVO JACK



INVERTED ROTATING BALL SCREW SERVO JACK

