

Screw Driven automation tables

Precise multi-axis positioning systems play an integral part in today's semiconductor, computer peripheral, solar power, flat panel, life sciences, lab automation, biomedical and electronics industries. The demands for tighter specifications, improved throughput and consistent quality have become increasingly stringent. Because of the complexity associated with these systems, many manufacturers insist on a single source supplier to eliminate multiple vendor design incompatibilities and delivery conflicts. With over forty years' experience as a global leader in the development of products and technology, Parker provides the most advanced, easy to integrate high-precision electromechanical systems.

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402/403XE Series Positioners

Features

- Integrated bearing
- Rigid steel body
- Significant force per dollar value
- Easily integrated into multi-axis designs
- Adjustment free
- Small package size

Reliable, Cost-Effective Positioning

The 402/403XE series of positioners combines a rugged steel body construction with an integrated precision ballscrew and bearing guide to produce a highly accurate, cost-effective line of positioners ideal for applications in the hard disk, semiconductor, medical, machine building and many other industries.







Common Performance Specifications

Specifications	Unito	402	XE	403XE		
Specifications	Units	2 mm Lead	5 mm Lead	5 mm Lead	10 mm Lead	
Repeatability	μm	±	5	± 5		
Flatness	μm	15	5	see k	below	
Straightness	μm	18	5	see k	below	
Breakaway Torque	Nm	0.0	6	0.	15	
Maximum Input Speed	RPS	90)	see k	below	
Maximum Normal Load	kg	90)	16	50	
Maximum Inverted Load	kg	90)	16	60	
Static Permissible Pitch Moment	Nm	46	3	1()1	
Static Permissible Roll Moment	Nm	13	4	260		
Static Permissible Yaw Moment	Nm	5	l	120		
Torsional Pitch Stiffness	Arc-second/Nm	17.	17.7		.2	
Torsional Yaw Stiffness	Arc-second/Nm	11.	8	6	.1	
Torsional Roll Stiffness	Arc-second/Nm	5.9	9	5	.9	
Drive Screw Diameter	mm	8		1	0	
Drive Screw Efficiency	%	90)	9	0	
Linear Bearing Coefficient of Friction		0.0)1	0.	01	
Running Torque	Nm	0.0	5	0.	10	
Maximum Axial Load	Kg	13	17	31	27	
Moment of Inertia X of Guide Rail	mm ⁴	1.44 E	E+04	3.88	E+04	
Moment of Inertia Y of Guide Rail	mm ⁴	1.37 E	E+05	3.14 E+05		
Weight of Carriage	kg	0.2	6	0.3		
Maximum Acceleration	g's	2		2		
Allowable Duty Cycle	%	10	0	1(00	

402XE Specifications

		T01	T02	Т03	T04
Specifications	Units	(70 mm)	(120 mm)	(170 mm)	(220 mm)
402XE with 2 mm Lead					
Accuracy over travel	μm	70	75	85	90
Input Inertia	x10 ⁻⁶ (Kg-m ²)	0.615	0.772	0.929	1.09
Weight of Total Table	Kg	1.19	1.40	1.60	1.81
402XE with 5 mm Lead					
Accuracy over travel	μm	70	75	85	90
Input Inertia	x10 ⁻⁶ (Kg-m ²)	0.741	0.898	1.06	1.21
Weight of Total Table	Kg	1.19	1.40	1.60	1.81

403XE Specifications

	Units	T01 (55 mm)	T02 (105 mm)	T03 (205 mm)	T04 (305 mm)	T05 (305 mm)	T06 (505 mm)	T07 (605 mm)	T08 (655 mm)
403XE with 5 mm Lead									
Travel Accuracy	μm	70	80	90	95	100	110	120	n/a
Flatness	μm	15	15	15	15	25	25	25	n/a
Straightness	μm	15	15	15	15	25	25	25	n/a
Maximum Input Speed	RPS	80	80	80	80	80	80	60	n/a
Input Inertia	x10 ⁻⁶ (Kg-m ²)	1.72	2.10	2.87	3.63	4.40	5.17	5.93	n/a
Weight of Total Table	Kg	1.85	2.25	2.85	3.55	4.25	4.85	5.55	n/a
403XE with 10 mm Lead									
Accuracy over travel	μm	70	80	90	95	100	110	120	130
Maximum Input Speed	RPS	80	80	80	80	80	80	60	42
Input Inertia	x10 ⁻⁶ (Kg-m ²)	2.50	2.88	3.65	4.42	5.18	5.95	6.7	7.10
Weight of Total Table	Kg	1.85	2.25	2.85	3.55	4.25	4.85	5.55	5.85

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402/403XE Load-Life Performance

The following performance information is provided as a supplement to the product specification pages. The useful life of a linear table at full catalog specifications is dependent on the forces acting upon it. These forces include both static components resulting from payload weight, and dynamic components due to acceleration/ deceleration of the load. In multi-axis applications, the primary positioner at the bottom of the stack usually establishes the load limits for the combined axes. When evaluating life versus load, it is critical to include the weight of all positioning elements that contribute to the load supported by the primary axis. The following graphs are used to establish the table life relative to the applied loads. For more information, download the product manual at www.parkermotion.com or contact our applications department at (800) 245-6903.







Screw Driven Tables





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Screw Driven Tables

The 402/403XE Series offers complete flexibility, from motor-mounting options to cleanroom compatability and a variety of offerings in between. Whether the application calls for a hardcover protection for the linear guide, cleanroom-compatible solutions, custom motors mounted at the factory, or an aesthetically appealing engineered limit sensor package, the 402/403XE can be customized to fit the task at hand.

Motor Mounting Flexibility



With standard options for the NEMA 17, NEMA 16, NEMA 23, and other Parker Automation motors, the 402/403XE allows the user to select the motor of their choice without being restricted to one model. To further customize the application solution, the 402/403XE can be ordered ready to mount onto most other manufacturers' motors as well.

Low-Profile Design



The highly integrated ballscrew and guide bearing design allows for a greatly reduced overall height when compared to traditional stacking of a bearing and screw assembly. This results in a more compact footprint.

Rigidity



With the steel U channel body and integrated bearing design, the structural rigidity of the 402/403XE is significantly stiffer than most aluminum body positioners. The increased stiffness results in reduced overall cost due to the elimination of support structures.

Hardcover Protection



For added protection to the bearing system and drive train, an optional hardcover is available. This will bring the positioner to an IP20 rating and prevent large particles from entering and damaging the screw or bearings.

Cleanroom & Raydent Coatings

Cleanroom ratings are possible with the XE product. The actual cleanroom rating will be dependent upon such variables as the location of the sniffer device, the velocity of the table, etc. Consult the factory for specific cleanroom-capability details or test results.

Riser Plates

Most of the motors used with the 402/403XE and some of the 404XE motors have a taller profile than the positioner. Thus the motor can interfere with the



positioner mounting surface. To accommodate riser plates can be provided to space the unit above the mounting surface. See XE product Manual for dimensional details and part numbers. Also available are X-Y transition plates for XE to XE and LP mounting.

402/403XE Demo Units



Order 803-0346 for a multi-axis demo unit to learn the product and display for shows and presentations. The demo will come in a watertight pelican carrying case and will be ready for demonstration programmed from the factory.





Packaged Limit Sensors

Limit sensor flexibility allows for a completely packaged sensor kit with a connectorized cable and a single cable to manage multi-axis solutions. It also allows for a simpler sensor pack out of which the sensor wires exit in a flyingleads style with 3 meters of cable from the point of the sensor. To further accommodate each application's unique needs, the sensors can be specified as NPN, PNP, normally open, or normally closed varieties. With the unmatched design, the sensor pack on the 402/403XE allows for fully adjustable sensors along the travel length of the positioner, which creates no pinch points for other cables or hoses to be sliced.

The limit/home switch installed on the 402XE and 403XE is a Hall effect sensor tripped by a magnet located in a housing attached to the carriage. On the switch body is an LED to indicate activation. Normally open sensors are typically used for home and normally closed are typically used for limits. With a current sinking sensor, the output lead provides a path to ground when activated, and with a current sourcing sensor, the output lead provides a positive (+) voltage potential relative to ground. Refer to your controller's manual for compatibility. Limit/home switch information is below.

Limit sensor mounting screws are reverse-thread style so tightening the screw loosens the limit sensor in the track and vice versa.







402/403XE

Wiring Code

Power (+)	Brown
Output Signal	Black
Ground (-)	Blue

402/403XE Sensor Pack Wiring Code

Red
Blue
Orange
Green
Blue
Green w/ Yellow Stripe

(1) Limit 1 is the switch farthest from the connector on the sensor pack housing; Limit 2 is the switch closest to the connector.

402/403XE Home/Limit Switch Specifications

	Units	H2 or L2 Option	H3 or L3 Option	H4 or L4 Option	H5 or L5 Option	H11 or L1 ⁻ Optio	H12 1 or L12 n Option	H13 or L13 Option	H14 or L14 Option
Switch Type		N.C.	N.O.	N.C.	N.O.	N.C.	N.O.	N.C.	N.O.
Logic		NPN	NPN	PNP	PNP	NPN	NPN	PNP	PNP
Operating Voltage	VDC		10-30						
Voltage Drop	VDC (Max)		2.5						
Continuous Current	mA				10	0			
Repeatability	µ (Max)				10	00			
Reverse Polarity Protection					Ye	es			
Short-Circuit Protection					Ye	es			
Power-Up Pulse Suppression	า				Ye	es			
Enclosure Rating			IP67						
Operating Temperature	° C				-25 tc	+75			
Cable Length	m		3.0 m fro	m Switch		3	3.0 m from end	of Sensor F	Pack





Dimensions (mm)

402XE with Hardcover



Order Code	Travel	"A"	"B"	"F"	"G"	"H"	"J"
T01	70 mm	168.0	87.5	1	80.0	4	35.0
T02	120 mm	218.0	112.5	2	160.0	6	20.0
т03	170 mm	268.0	137.5	2	160.0	6	45.0
T04	220 mm	318.0	162.5	3	240.0	8	30.0

402XE without Hardcover

Motor Option	Motor or Motor Size	L	М	N	R
M2	SM16/BE16	8.0	40.6	40.6	-
M3	NEMA23/SM23	8.0	57.2	57.2	-
M37	NEMA17	8.0	43.0	37.0	-
M41	SM162AQ-NPSN	8.0	37.0	40.6	136.7
M46	HV232-02-10	8.0	57.2	57.2	71.1
M61	BE23	15.0	57.2	57.2	-

www.parkermotion.com

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403XE with Hardcover

Dimensions (mm)

Order Code	Travel	"A"	"B"	"F"	"G"	"H"	"J"
T01	55 mm	174.0	93.5	1	100.0	4	25.0
T02	105 mm	224.0	118.5	1	100.0	4	50.0
T03	205 mm	324.0	168.5	2	200.0	6	50.0
T04	305 mm	424.0	218.5	3	300.0	8	50.0
T05	405 mm	524.0	268.5	4	400.0	10	50.0
T06	505 mm	624.0	318.5	5	500.0	12	50.0
T07	605 mm	724.0	368.5	6	600.0	14	50.0
T08	655 mm	774.0	383.5	7	700.0	16	25.0

Motor Option	Motor or Motor Size	L	М	N	R
M2	SM16/BE16	8.0	40.6	40.6	-
M3	NEMA23/SM23	8.0	57.2	57.2	-
M37	NEMA17	8.0	55.0	37.0	-
M41	SM162AQ-NPSN	8.0	40.6	40.6	136.7
M42	SM232AQ-NPSN	8.0	57.2	57.2	126.5
M46	HV232-02-10	8.0	57.2	57.2	71.1
M61	BE23	15.0	57.2	57.2	-

403XE without Hardcover

Fill in an order code from each of the numbered fields to create a complete model order code.

			0	2	3	4	5	6	0	8	9	10	1		
		Order Example:	402	T03	XE	S	D9	H4	L5	M2	C3	R11	P1		
1	Series 402	8	Mo M1 M2	Motor MountM1MTR block coupling housing onlyM2MTR block with flange kit for SM16											
2	Travel T01* T02 T03 T04 * Limited or H5L1 h	YravelM3MTR block with flange kit for NEMA 23Y01*70 mmM37MTR block with flange kit for NEMA 17Y02120 mmM41*SM162AQ-NPSN motor mountedY03170 mmM46**HV232-02-10 stepper motor mountedY04220 mmM61MTR block with flange kit for BE23Limited to H1L2, H1L3, H1L4, H1L5, H1L1, or H2L1, H3L1, H4L1, or H5L1 home and limit options*Order with C2 or C3 coupling option											} ,		
3	Family XE	XE Series					0	Mo C1 C2	tor C	ouplin Not req 0.25" C	g uired Idham				
4	Grade S	Standard Grade						C3 C4 C5		0.25 B 0.375" 0.375"	Oldhar Bellow	m vs			
5	Drive S D2 D9	e Screw 5 mm 2 mm							C24 5 mm Oldham C25 5 mm Bellows						
							10	Env	vironr	nental	Optic	ons			
6	Home S	Sensor						R11	*	Hard co	over				
	H1	No home sensor						RI2		Hard Co	over, ci	eanroor	n prep		
	H2	N.C. sinking, flying leads						RIJ	*		er er eler				
	H3 H4 H5	N.O. sinking flying leads N.C. sourcing, flying leads N.O. sourcing, flying leads						* Cle to va	anroor ariation	n class i of comp	rating sl patibility	hould be at differe	prep checke ent spee	ed for each a eds	application due
	H11*	N.C. sinking, sensor pack					ເພ	Ort	hoqo	nality	Optio	ns			
	H12*	N.O. sinking, sensor pack					Ŭ	P1		X axis f	or sing	le axis			
	H13*	N.C. sourcing, sensor pack						P20	*	X axis f	or X-Y	assemb	oly mot	or @ 12:00)
	H14*	N.O. sourcing, sensor pack						P43	*	Y axis f	or X-Y	assemt	oly mot	tor @ 3:00	
	* Must be	e ordered with L11, L12, L13, or I	_14 limit	option				P49	*	Y axis f	or X-Y	assemb	oly mot	tor @ 9:00	
0	Limit Sensor							* Pin Cont	ning to tact fao	o 130 ard ctory for	c-sec or details.	rthogona	lity. Adc	ditional brack	keting required.
	L1	None													
	L2	N.C. sinking, flying leads													
	L3	N.O. sinking, flying leads													
	L4	N.C. sourcing, flying leads													
	L5	N.O. sourcing, flying leads													
	L11	N.C. sinking, sensor pack													
	L12	N.O. sinking, sensor pack													

L14 N.O. sourcing, sensor pack

Screw Driven Tables

Fill in an order code from each of the numbered fields to create a complete model order code.

			1	2	3	4	5	6	0	8	9	10	1			
		Order Example:	403	T04	XE	S	D2	H3	L2	M4	C3	R13	P1			
1	<mark>Series</mark> 403	60 mm														
0	Travel T01* T02* T03 T04 T05 T06 T07	55 mm 105 mm 205 mm 305 mm 405 mm 505 mm 605 mm					0	M3 M37 M41 M46 M61 * Ord ** Ord	r f * S *** H ler with der with	MTR blo MTR blo SM162/ HV232- MTR blo n C2 or (th C4 or	ock wit ock wit AQ-NF 02-10 ock wit C3 coup C5 cou	th flange th flange SN mot stepper th flange pling option pling option	e kit foi or mo moto kit foi kit foi on	r NEMA r NEMA unted r mount r BE23	23 17 ed	
	T08** * Limited t or H5L1 h ** Only av	655 mm to H1L2, H1L3, H1L4, H1L5, H1 nome and limit options ailable with D3 drive option	L1, or H2	2L1, H3L	.1, H4L	_1,	U	C1 C2 C3 C4	1)))	Not req 0.25" O 0.25" B 0.375" (uired Idham ellows Oldhan	n				
3	Family XE	XE Series						C5 C24 C25	(5	0.375" 5 mm C 5 mm B	3ellow: Idham ellows	S				
4	<mark>Grade</mark> S	Standard Grade					10	<mark>Env</mark> R11	ironn	nental Hard co	Optio ver	ons				
5	Drive S D2 D3	crew 5 mm 10 mm						R12 R13 R14 * Clea	ל * מורכי anroor	Hard cc No cove No cove n class r	ever, clear er, clea ating sh	eanroon Inroom p nould be	n prep orep checke	ed for ead	ch applica	tion due
6		Sensor						to va	riation	of comp	atibility	at differe	ent spee	əds		
	H2 H3 H4 H5 H11* H12* H13* H14* * Must be	N.C. sinking, flying leads N.O. sinking flying leads N.C. sourcing, flying leads N.O. sourcing, flying leads N.C. sinking, sensor pack N.O. sinking, sensor pack N.O. sourcing, sensor pack N.O. sourcing, sensor pack ordered with L11, L12, L13, or L	_14 limit o	option			0	Orth P1 P20 P43 P49 * Pini Cont	nogoi *) * *	nality (X axis fo X axis fo Y axis fo Y axis fo 130 arc story for	Dption or singlor X-Y or X-Y or X-Y -sec or details.	ns le axis assemb assemb assemb thogonal	ly mot ly mot ly mot ity. Adc	or @ 12 or @ 3: or @ 9: litional bi	1:00 00 00 racketing	required.
0	Limit So L1 L2 L3 L4 L5 L11 L12 L13	ensor None N.C. sinking, flying leads N.O. sinking, flying leads N.C. sourcing, flying leads N.O. sourcing, flying leads N.C. sinking, sensor pack N.O. sinking, sensor pack N.C. sourcing, sensor pack														

